

Air Force Research Laboratory Space Vehicles Directorate

Overview – Space Applications and Opportunities

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## Challenges of Modern Space Systems

- Current systems are large and complex
  - Expensive to design, build and launch
  - Long development times, technically obsolete at launch
  - Launch Costs are Prohibitive
  - Static designs with no adaptability to evolving world situations and threats



New paradigms required to change the order of business for Air Force

- Basic rethinking of space system architectures
- Simultaneous attack on performance and cost



## Space Applications that Need Tech Insertion

- Large Optical Systems
  - Surveillance and Directed Energy
- High Power Spacecraft
  - Large PV Arrays
- Launch Environment Mitigation
  - Vibration, Acoustics, and Shock
- Docking for On-Orbit Servicing
  - Smart Docking Mechanisms vs. Smart Servicing S/C



## Large Space Optics Technology Needs

#### **Next Generation Space Telescope**

Cryogenic
Inflatable Sun Shield



#### Common

Adaptive Optics
Lightweight Mirrors
Lightweight Structures
Mechanisms
Precision Structures
Micro-dynamics
Wavefront Sensors
Integrated Controls
End-to-End Integrated Modeling

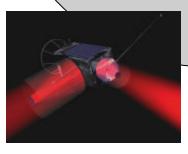
#### **Space-based Laser**

Thermal Control ATP/FC Laser Disturbance



#### **Relay Mirror**

Gimbaled Telescopes
Laser Beacon on
Articulated Boom
Beam Cleanup
Momentum Control

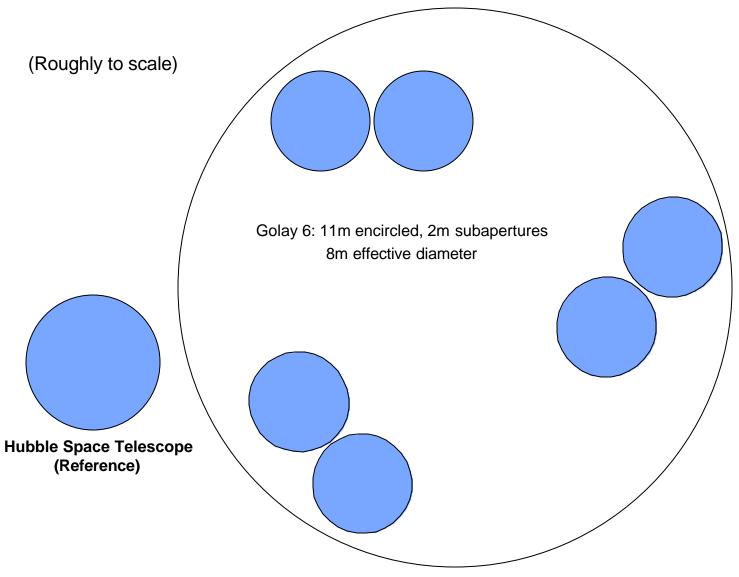


## Tactical Imaging Agile Targeting

Geolocation Inertial Reference



## **Aperture Comparison Summary**





## Launch Vehicle Constraints on Maximum Satellite Size and Weight

Space Shuttle



Titan IV





**EELV** 



- All available choices currently constrained by ~5 m diameter
- Available weight depends on specific launch vehicle and orbit

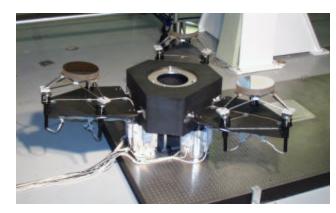


### Lightweight Space Optics Technical Needs

- Lightweight Mirrors
  - Scalable approaches to large-aperture lightweight mirror structures
- Lightweight Precision Structures
  - High-stiffness structures providing optical precision dimensional stability
- Deployment Mechanisms for Optical Systems
  - Precision deployment mechanism concepts for space optics systems.
- Integrated Opto-Mechanical Control Systems
  - Innovative, traceable approaches to high-performance control systems
- End-to-End Integrated Modeling
  - Tools & software to provide system-level performance and trades



## AFRL's Deployable Optical Telescope (DOT)

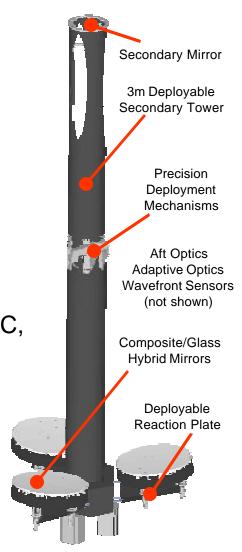


#### Objectives:

- phasing & maintenance of segmented primary mirror
- deployment, capture, and maintenance of secondary mirror
- Demonstration of traceable control algorithms, WFS/WFC, mechanisms, and advanced actuators

#### Testbed Description

- f/20 sparse phased-aperture telescope
- 3 sub-apertures, fill factor = 29%
- 1.7 m encircled aperture dia. (1.5 m eff)
- 0.6 m sub-aperture diameter





## Technical Metrics/Goals

|  | Goal                                       | Current Values         |  |
|--|--|------------------------|--|
| Sub-Aperture Phasing                     |  |                        |  |
| Accuracy (segment-to-segment OPD)        | 0  | < 1 nm (1/600 wave)    |  |
| Complexity, Autonomy, Traceability, Cost | Min/Max, Subjective                        |                        |  |
| Deployment mechanisms                    |  |                        |  |
| Accuracy                                 | < 10 microns                               | *                      |  |
| Repeatability                            | 1 micron (2 •)                             | *                      |  |
| Stability                                | Incidence frequency, magnitude, hysteresis | *                      |  |
| Deployed Stiffness                       | 1 M lb/in (SBL)                            | *                      |  |
| Precision Structures                     |  |                        |  |
| Dimensional Stability                    | Expansion coefficients                     | ?                      |  |
| Stiffness (1 <sup>st</sup> mode)         | >40 Hz                                     | 25-30 Hz               |  |
| Lightweight Mirror Structures            |  |                        |  |
| Areal Density                            | < 10 kg/m <sup>2</sup>                     | < 12 kg/m <sup>2</sup> |  |
| Surface accuracy                         | < 1/30 wave rms                            | > 1 wave rms           |  |
| Radius of curvature matching             |  | *                      |  |



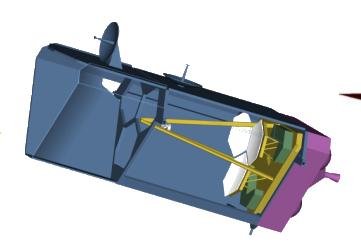
### **Role for Smart Materials**

- Actuators
  - Huge Dynamic Range (nm to cm)
  - Compact and Light (including electronics!!!)
  - Space Survivable
- Reliable, Stable Deployment Mechanisms
- Damping Treatments for High Stiffness Structures
  - Exploit nonlinear characteristics of smart materials for passive damping and isolation

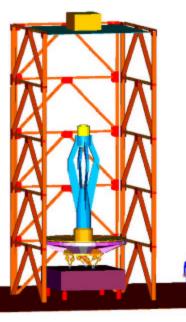


## Space-Based Laser

- SBL Beam Director Element
  - AFRL SPICE facility currently baselined
  - SBL structural risk reduction testbed
- NEXUS
  - NASA Deployable Optics Flight Experiment
  - Anticipated launch in late 2004
  - 3-meter segmented telescope design
  - NGST- scale deployment mechanisms



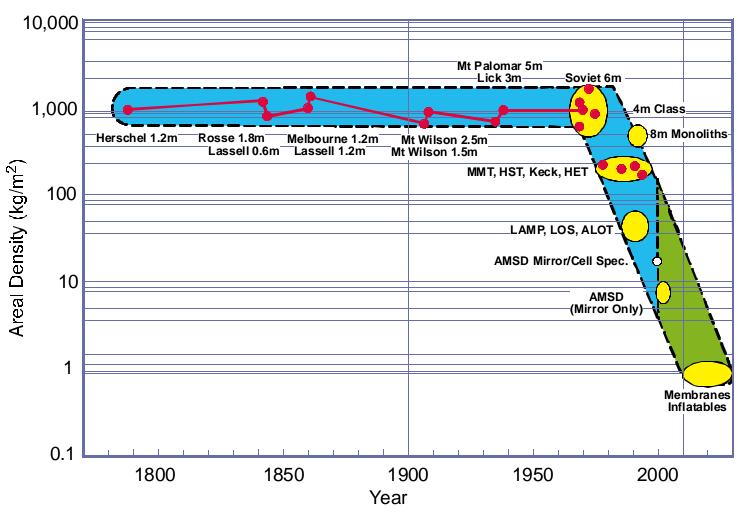




**BDE Testbed Concept** 



## AMSD is an Integral Component of Large Optics Revolution



**Approximate Area Density of Large Mirrors 1789-2030** 



### **Advanced Lightweight Mirrors**

#### **Motivation:**

Mirrors are principle driver of mass and volume for large optical space systems. Economical, reliable methods of producir large numbers of lightweight (15kg/m^2) not exist.

ACTUATORS NOW DRIVING MIRROR SYSTEM MASS!!

#### **Technical Objectives:**

Areal Density < 15 kg/m

Shape Hexagonal

Petal Size Between 1.2 and 1.5m

Operating Temp.:

Ambient 300 +/- 10 K Cryo 35 +20 /- 5 K

#### **Future: Membrane Optics**

Areal Density ~1 kg/m





### Precision Deployed Structures

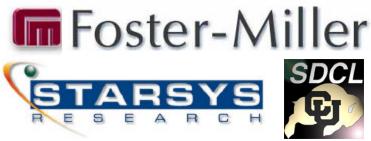
#### **Technical Objectives**

- Development of precision deployment concepts
  - High stiffness-mechanisms
  - Deterministic load-bearing deployment
  - Sub-wavelength passive stability

#### **Program Description**

- Contract (SBIR) Efforts
  - Starsys Phase-I
    - Zero-force precision latch (E-K interest)
  - Foster-Miller Phase-II
    - Integral Hinge Mechanisms (E-K interest)
  - Foster-Miller Phase-I
    - Precision latch
- Collaborative Research
  - NASA LaRC low-hysteresis hinges
- In-house mechanism testing in PDOS facility







### Vibration Isolation and Suppression System (VISS) Successfully Launched

#### **Technical Objectives**

- Demonstrate stable precision sensor platform
- Demonstrate suppression of tonal disturbances
- Demonstrate steering for imaging applications

#### Program Description

- BMDO sponsored hardware development effort
- AFRL and JPL: software, controller design, performance and qualification testing
- Integrated with STRV-2 Experiment Module on TSX-5 satellite

#### **Hardware Description**

- Six hybrid actuators
  - Passive isolation using D-Strut TM elements
  - Active isolation, steering, and vibration suppression using magnetic voice coils
- Stewart Platform configuration
- Re-programmable flight electronics
- Supports DERA (MOD) MWIR imager







## Honeywel 🗑





#### Status

- TSX-5 launch date 07 June 2000
- VISS turn-on ~20 June 2000
- VISS Engineering model delivered to AFRL 31 May 2000
- VISS Mission Ops team ready

**NEXT STEP:** Need to Miniaturize!!



### Technology Challenge: High Power Space Systems

- Many Current Systems Are Power Constrained:
  - GPS IIF uses less power than a common hairdryer

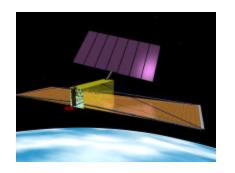


GPS Satellite
1000 Watts

Hairdryer 1200 Watts



Significant Increase in Power Required for Future Systems



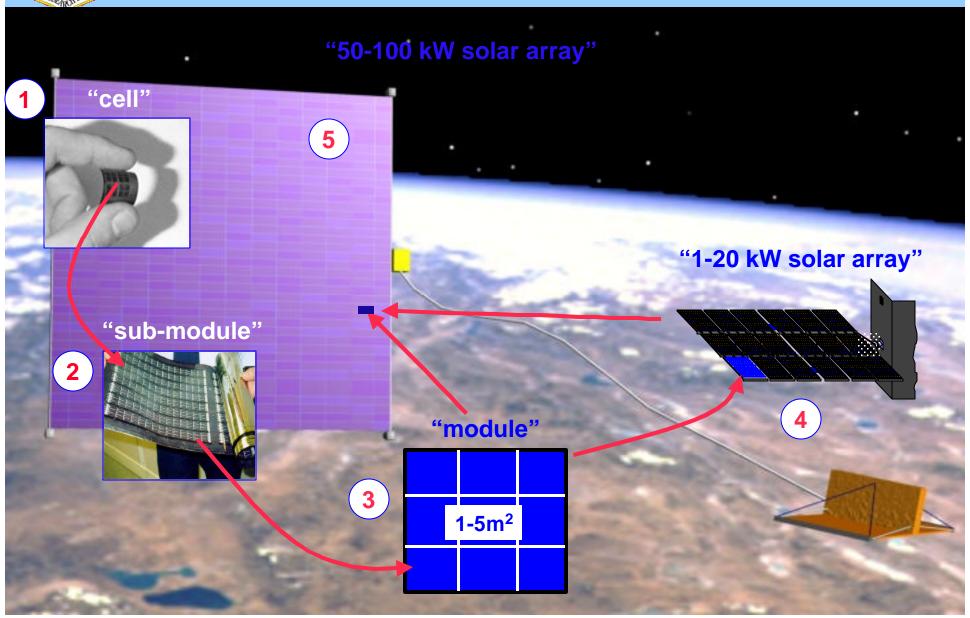
**Space Based Radar - Space Based Laser** 

25kW - 100 kW

Eliminate Power From The Space Equation



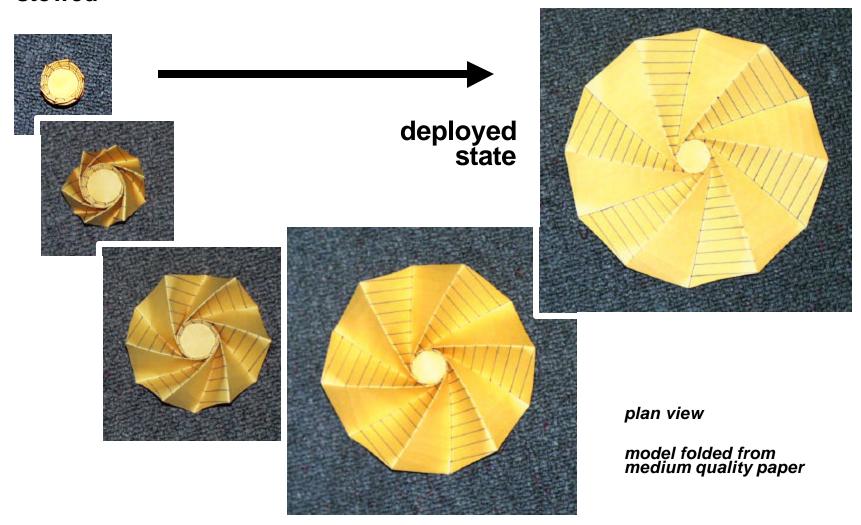
## AFRL Power Sail Program





# Deployment Sequence: Origami in Space??

#### stowed

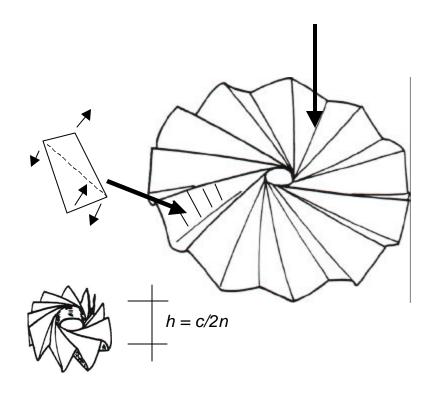




## Features of Stowage and Deployment

- The panels bend/twist but do not shear during deployment
- The panel sizes vary greatly
- The stowed package is long if n is not sufficiently large

Elastic spars along the spiral folds





# Comparison of Solar Cell Technologies

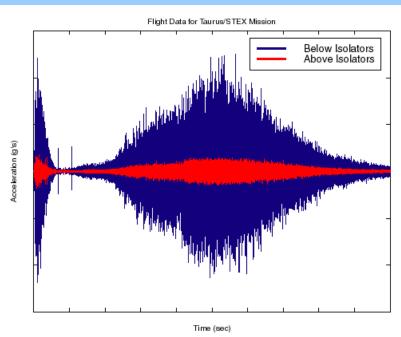
| Array Type  | AM0 BOL<br>Efficiency           | Panel Configuration                          | Operating<br>Temp<br>(deg C) | Temp.<br>Factor | Radiation<br>Factor | EOL<br>Specific<br>Power<br>(W/kg) |
|---|---------------------------------|--|------------------------------|-----------------|---------------------|------------------------------------|
| State of practice, 5.5<br>mil GaAs/Ge on rigid<br>substrate | 18.5%                           | Gr/Ep Al H/C Gr/Ep                           | 60                           | 0.93            | 0.82                | 36                                 |
| 3-Junction on rigid substrate                               | 24.0%<br>24.0% w/<br>1.7X conc. | Gr/Ep Al H/C Gr/Ep                           | 60                           | 0.93            | 0.82                | 47<br>80                           |
| 4-Junction on rigid substrate                               | 35.0%<br>w/1.7X<br>conc.        | Gr/Ep Al H/C Gr/Ep                           | 60                           | 0.93            | 0.82                | 116                                |
| FTFPV<br>(CIGS or a-Si)<br>on polyimide*                    | 10%<br>15%<br>20%               | 5 mm CIS or a-Si 1.5 mil polyimide substrate | 75                           | 0.76            | 0.97                | 350<br>525<br>700                  |
| FTFPV<br>(CIGS or a-Si)<br>on stainless steel*              | 10%<br>15%<br>20%               | 5 mm CIS or a-Si 1 mil stainless steel       | 75                           | 0.76            | 0.97                | 255<br>380<br>510                  |
| Holy-Grail!! III-V-based thin- film on flex structure*      | 35%                             | 5 mm III-V MJ<br>1.5 mil polyimide           | 60                           | 0.93            | 0.85-0.95           | 1225                               |

<sup>\*</sup> Array support structure is 0.1kg/m<sup>2</sup> FTFPV blanket, interconnects, cabling and thermal control included



### Taming the Launch Environment: New Success in Launch Isolation





Stex Flight Data

1<sup>st</sup> Generation

Axial Only

Three Successful Taurus Launches: GFO, STEX, MTI



### **OSP/JAWSAT SPECIFICS**

Isolation System Properties

- Mass: 25.61 lbs

— Height : 3.5"

Additional 0.5" and 4.1 lbs
 Added for This Mission

 Flight Data Concurs with Coupled-Loads Analysis

 JAWSAT Satellite consisted of Five Small Satellites

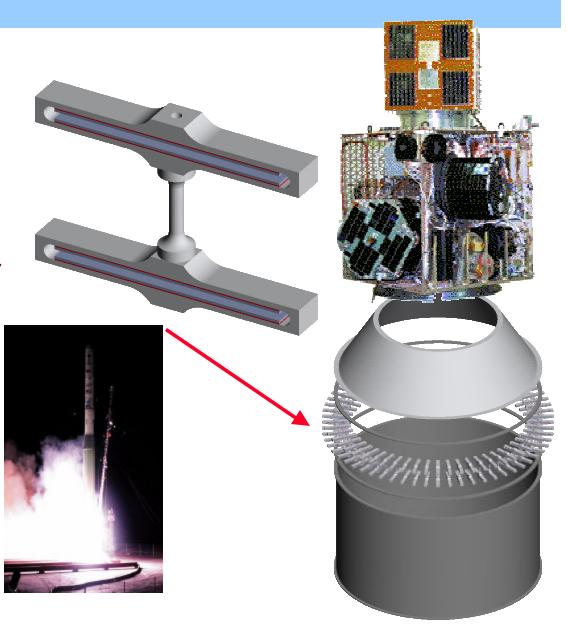
- FALCONSAT - Air Force Academy

- JAWSAT Frame - OSSS and NASA

- OSCE - AFRL/DE

- OPAL - Stanford

- ASUSAT - Arizona State

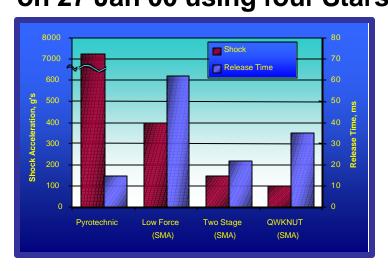


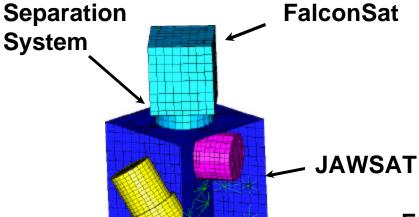


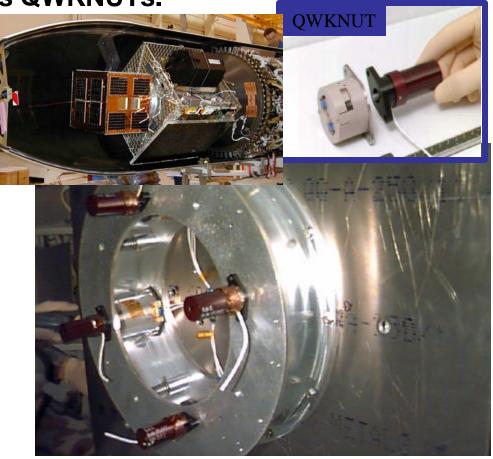
## Taming the Launch Environment: Low Shock Release of FalconSat on OSP-1

STARSYS

 Air Force Academy FalconSat was successfully deployed from OSP-1 on 27 Jan 00 using four Starsys QWKNUTs.







FalconSat Separation System on the test stand



## Lightweight Flexible Solar Array (LFSA) Integrated Subsystem Demonstration

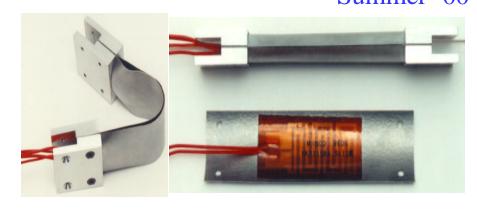
#### **LFSA Benefits**

- Demonstrate Specific power >100Watts/kg compared to 40Watts/kg
- Uses CuInSe2 (CIS) 8.6% thin film solar cells on flex Poly
- SMA hinge and deployment systems for controlled deployment
- Low stowage volume
- MFS PV substrates with integral traces leading to 30% mass cut in cable harness





LFSA Demonstration Panel EO-1 Spacecraft
Summer '00



Shape Memory Alloy Hinge Successfully Demonstrated on Shuttle



# Historical Challenges of Space Servicing

## Impediments to Current Space Servicing

- Costs more to service than to replace
- Takes too long
- Limited repairability of satellites





IntelSat VI Rescue Mission \$96M (Hughes) + \$450M (NASA)





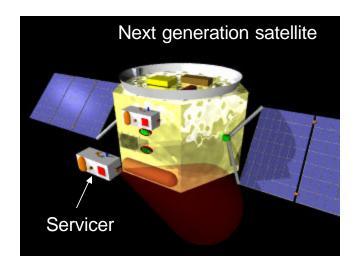
**Hubble Repair Mission \$674M** 

Inexpensive, Simple Autonomous Operations, and Fast Response Servicers Are Required to Make Space Servicing Routine



## Elements Required for Inspection and Servicing of Space Assets

- Satellite designed for onorbit servicing
  - Open architecture backbone
    - e.g., PC-like bus
  - Ports available from outside



- Autonomous, low cost, vision-guided inspector/servicer
  - Finds, inspects, docks and services
  - Provides satellite visual assessments, replaces modular components, and replenishes expendables

Revolutionary paradigm shift in satellite design and operations



### Conclusion

- Time is Ripe for the Insertion of Smart Structures and Materials into Space Systems
  - Recent Space Demonstrations
  - More Stringent Requirements
- Military Systems
  - Low Cost
  - Large Aperture
  - Launch Costs
- AFRL Focus
  - Rapid Transition through Demonstration
  - Requires Inter-Government as Well as Industry Cooperation (\$\$)